## **Instrument I**

## **ROBOT TRUST QUESTIONNAIRE**

Please mark the percentage for each question.

What percentage of the time do you believe this robot will	%										
	0	10	20	30	40	50	60	70	80	90	100
1) Function successfully?											
2) Act consistently?											
3) Reliable?											
4) Predictable?											
5) Dependable?											
6) Follow directions?											
7) Meet the needs of the mission?											
8) Perform exactly as instructed?											
9) Have errors?											
10) Provide appropriate information?											
11) Unresponsive?											
12) Malfunction?											
13) Communicate with people?											
14) Provide feedback?											

Schaefer, K. (2013). *The perception and measurement of human-robot trust.* (Unpublished doctoral dissertation). University of Central Florida, Orlando, FL.

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