**Attachment D**

**HuMAN-Robot Trust Questionnaire**

Please mark the percentage for each question.

|  |  |  |  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- |
| **What percentage of the time do you believe this demolition robot will…** | **%** | | | | | | | | | | |
| **0** | **10** | **20** | **30** | **40** | **50** | **60** | **70** | **80** | **90** | **100** |
| 1. Function successfully? |  |  |  |  |  |  |  |  |  |  |  |
| 1. Act consistently? |  |  |  |  |  |  |  |  |  |  |  |
| 1. Reliable? |  |  |  |  |  |  |  |  |  |  |  |
| 1. Predictable? |  |  |  |  |  |  |  |  |  |  |  |
| 1. Dependable? |  |  |  |  |  |  |  |  |  |  |  |
| 1. Follow directions? |  |  |  |  |  |  |  |  |  |  |  |
| 1. Meet the needs of the mission? |  |  |  |  |  |  |  |  |  |  |  |
| 1. Perform exactly as instructed? |  |  |  |  |  |  |  |  |  |  |  |
| 1. Have errors? |  |  |  |  |  |  |  |  |  |  |  |
| 1. Provide appropriate information? |  |  |  |  |  |  |  |  |  |  |  |
| 1. Unresponsive? |  |  |  |  |  |  |  |  |  |  |  |
| 1. Malfunction? |  |  |  |  |  |  |  |  |  |  |  |
| 1. Communicate with people? |  |  |  |  |  |  |  |  |  |  |  |
| 1. Provide feedback? |  |  |  |  |  |  |  |  |  |  |  |

Schaefer, K. (2013). *The perception and measurement of human-robot trust.* (Unpublished doctoral dissertation). University of Central Florida, Orlando, FL.